

solution

Thursday, March 3, 2022 2:18 PM

- Each of the following questions must be answered with YES or NO. If the answer is YES, an example must be given — not an explanation. If the answer is NO, an explanation is needed.

(a) Is there a surjective linear map $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which is not injective?

Answer: NO. If F is a surjective linear map, then $\dim \text{Im} F = 2$. By the dimension theorem $\dim \text{Ker} F = 2 - \dim \text{Im} F = 0$, so $\text{Ker} F = 0$, which means F is injective.

(b) Is there a symmetric 2×2 matrix that is not positive definite?

Answer: YES, e.g., the zero matrix.

(c) Is there a 2×2 matrix that is not diagonalisable?

Answer: YES, e.g., $\begin{pmatrix} 1 & -2 \\ 1 & -1 \end{pmatrix}$ has no real eigenvalue so is not diagonalisable.

- Determine whether the subset $\mathbb{U}$ is a subspace of the vector space $\mathbb{V}$. Justify your answer.

(a) $\mathbb{V} = \mathbb{P}_2$ and $\mathbb{U} = \{p \in \mathbb{V} \mid p'(x) = x\}$.

Answer: The zero element does not belong to $\mathbb{U}$, so $\mathbb{U}$ is not a subspace.

(b) $\mathbb{V} = M_{2 \times 2}(\mathbb{R})$ and $\mathbb{U} = \{A \in M_{2 \times 2}(\mathbb{R}) \mid A = A^t\}$.

Answer: It is a subspace because:

- $0^t = 0$, so $0 \in \mathbb{U}$. In particular, $\mathbb{U}$ is nonempty.
- If $A, B \in \mathbb{U}$, then $(A+B)^t = A^t + B^t = A+B$, and thus $A+B \in \mathbb{U}$.
- If $A \in \mathbb{U}$ and $\lambda \in \mathbb{R}$ then we have $(\lambda A)^t = \lambda A^t = \lambda A$, so $\lambda A \in \mathbb{U}$.

- Let $G: \mathbb{P}_2 \rightarrow \mathbb{P}_1$ be the linear map where

$$G(x^2) = x, \quad G(x) = x+1, \quad G(1) = x$$

and let $H: \mathbb{P}_1 \rightarrow \mathbb{R}^2$ be the linear map given by $q \mapsto (q'(0), q(0))$. Consider the bases $\underline{v} = (1, x, x^2)$ of $\mathbb{P}_2$, $\underline{u} = (1, x)$ of $\mathbb{P}_1$ and $\underline{e} = (e_1, e_2)$ of $\mathbb{R}^2$.

- Find $G_{\underline{u}}^{\underline{v}}$ and $H_{\underline{e}}^{\underline{u}}$.
- Is the composition $H \circ G$ a linear map? If yes, find the matrix $(H \circ G)_{\underline{e}}^{\underline{v}}$; if not, explain why.
- Is there a linear map $F: \mathbb{P}_2 \rightarrow \mathbb{P}_1$ with $F \neq G$ such that $H \circ F = H \circ G$? If yes, give an example of such F ; if not, explain why.

$$(a) \quad G_{\underline{u}}^{\underline{v}} = \begin{pmatrix} G(1)_{\underline{u}} & G(x)_{\underline{u}} & G(x^2)_{\underline{u}} \end{pmatrix} = \begin{pmatrix} (x)_{\underline{u}} & (x+1)_{\underline{u}} & (x)_{\underline{u}} \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

$$H_{\underline{e}}^{\underline{u}} = \begin{pmatrix} H(1)_{\underline{e}} & H(x)_{\underline{e}} \end{pmatrix} = \begin{pmatrix} 1'_{\underline{e}} & x'_{\underline{e}} \\ 1_{\underline{e}} & x_{\underline{e}} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$(b) \quad \text{yes, } (H \circ G)_{\underline{e}}^{\underline{v}} = H_{\underline{e}}^{\underline{u}} G_{\underline{u}}^{\underline{v}} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

(c) No, since H is invertible: if $H \circ F = H \circ G$ then

$$H^{-1} \circ H \circ F = H^{-1} \circ H \circ G = \text{Id} \circ G = G$$

$$F = \text{Id} \cdot F$$

4. Let

$$A = \begin{pmatrix} 4 & 4 & 9 & 0 & 35 \\ -1 & -1 & -2 & 0 & -8 \\ -3 & -3 & -7 & 0 & -27 \\ 1 & 1 & 2 & 0 & 8 \end{pmatrix}$$

- Find a basis of the column space of A .
- What is the dimension of the row space of A ?
- What is the dimension of the nullspace (kernel) of A ?

$$\begin{array}{ccccc} 4 & 4 & 9 & 0 & 35 \\ -1 & -1 & -2 & 0 & -8 \\ -3 & -3 & -7 & 0 & -27 \\ 1 & 1 & 2 & 0 & 8 \end{array} \xrightarrow{\substack{+1 \\ -3}} \begin{array}{ccccc} 0 & 0 & 1 & 0 & 3 \\ -1 & -1 & -2 & 0 & -8 \\ 0 & 0 & -1 & 0 & -3 \\ 0 & 0 & 0 & 0 & 0 \end{array} \xrightarrow{\substack{+1 \\ \times -1}} \begin{array}{ccccc} 0 & 0 & 1 & 0 & 3 \\ 1 & 1 & 2 & 0 & 8 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

$$\begin{array}{ccccc} 1 & 1 & 2 & 0 & 8 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

1st and 3rd columns form a basis to column space.

$$(a) \left(\begin{pmatrix} 4 \\ -1 \\ -3 \\ 1 \end{pmatrix}, \begin{pmatrix} 9 \\ -2 \\ -7 \\ 2 \end{pmatrix} \right)$$

$$(b) \dim(\text{row space}) \underset{\substack{\uparrow \\ \text{rank theorem}}}{=} \dim(\text{column space}) \underset{\substack{\uparrow \\ \text{by (a)}}}{=} 2$$

Alternatively, the above computation gives a basis to the row space which has two elements.

$$(c) \dim \ker A = 5 - \dim(\text{column space}) = 5 - 2 = 3$$

5. Equip $\mathbb{R}^3$ with the standard scalar product and consider the subspace $U = [(1, 1, 0), (1, 2, 2)]$ in $\mathbb{R}^3$. Let $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be given by the projection to U .

- Find an orthonormal (ON) basis in U .
- Find an ON basis in $U^\perp$.
- Find the matrix of F in an ON basis of your choice.
- Find the matrix of F in the standard basis.

(a) $\left(\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} \right)$ is a basis for U , so we apply Gram-Schmidt process to get an ON basis:

$$w_1 = \frac{v_1}{|v_1|} = \frac{1}{\sqrt{1^2+1^2+0^2}} v_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$$

$$\tilde{w}_2 = (v_2)_{\perp [v_1]} = v_2 - (v_2|w_1)w_1 = \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix} - \frac{1}{\sqrt{2}}(1 \cdot 1 + 1 \cdot 2 + 2 \cdot 0) \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1 \\ 1 \\ 4 \end{pmatrix}$$

$$w_2 = \frac{\tilde{w}_2}{|\tilde{w}_2|} = \frac{1}{\sqrt{18}} \begin{pmatrix} -1 \\ 1 \\ 4 \end{pmatrix}$$

Answer: $\left(\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \frac{1}{\sqrt{18}} \begin{pmatrix} -1 \\ 1 \\ 4 \end{pmatrix} \right)$

(b) $v_3 := \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}$ then $(v_3|v_1) = 0$ & $(v_3|v_2) = 0$ so $v_3 \in U^\perp$

$\dim U^\perp = 1$, so $w_3 = \frac{v_3}{|v_3|} = \frac{1}{\sqrt{9}} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}$ forms an ONB in $U^\perp$

(c) We take the ONB $(w_1, w_2, w_3) = \underline{w}$

Since $F(w_1) = w_1$
 $F(w_2) = w_2$
 $F(w_3) = 0$

$$[F]_{\underline{w}}^{\underline{w}} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

(d) Basechange: $(F)_{\underline{e}}^{\underline{e}} = T_{\underline{e}}^{\underline{w}} (F)_{\underline{w}}^{\underline{w}} T_{\underline{w}}^{\underline{e}}$

$$T_{\underline{e}}^{\underline{w}} = \frac{1}{3\sqrt{2}} \begin{pmatrix} 3 & -1 & 2\sqrt{2} \\ 3 & 1 & -2\sqrt{2} \\ 0 & 4 & \sqrt{2} \end{pmatrix} \quad \rightarrow \quad = \frac{1}{18} \begin{pmatrix} 3 & -1 & 2\sqrt{2} \\ 3 & 1 & -2\sqrt{2} \\ 0 & 4 & \sqrt{2} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & 3 & 0 \\ -1 & 1 & 4 \\ 2\sqrt{2} & -2\sqrt{2} & \sqrt{2} \end{pmatrix}$$

$$T_{\underline{w}}^{\underline{e}} = T_{\underline{e}}^{\underline{w}^{-1}} = \frac{1}{4} T_{\underline{e}}^{\underline{w}^t}$$

$$= \frac{1}{3\sqrt{2}} \begin{pmatrix} 3 & 3 & 0 \\ -1 & 1 & 4 \\ 2\sqrt{2} & -2\sqrt{2} & \sqrt{2} \end{pmatrix}$$

$$= \frac{1}{18} \begin{pmatrix} 3 & -1 & 0 \\ 3 & 1 & 0 \\ 0 & 4 & 0 \end{pmatrix} \begin{pmatrix} 3 & 3 & 0 \\ -1 & 1 & 4 \\ 2\sqrt{2} & -2\sqrt{2} & \sqrt{2} \end{pmatrix} = \frac{1}{18} \begin{pmatrix} 10 & 8 & -4 \\ 8 & 10 & 4 \\ -4 & 4 & 16 \end{pmatrix}$$

6. Let the vector space $V = M_{2 \times 2}(\mathbb{R})$ be equipped with a scalar product $(-|-)$ whose matrix in the basis

$\left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right)$ is

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 4 \end{pmatrix}.$$

(a) Find the length of $\begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix} \in V$.

Answer: The coordinate vector of $C := \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix} \in V$ in the given basis is $(0, 0, 1, 1)$. So $|C|^2 =$

6. Let the vector space $\mathbb{V} = M_{2 \times 2}(\mathbb{R})$ be equipped with a scalar product $(-|-)$ whose matrix in the basis

$\left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right)$ is

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 4 \end{pmatrix}.$$

(a) Find the length of $\begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix} \in \mathbb{V}$.

Answer: The coordinate vector of $C := \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix} \in \mathbb{V}$ in the given basis is $(0, 0, 1, 1)$. So $|C|^2 = (C|C) = 1 \cdot 0 + 1 \cdot 0 + 3 \cdot 1^2 + 4 \cdot 1^2 = 7$. The length of C is thus $\sqrt{7}$.

(b) For which $A \in \mathbb{V}$ is the map $F : \mathbb{V} \rightarrow \mathbb{R}$ given by $F(B) = (B|A)$ a linear map?

Answer: By the bilinearity of scalar product, the map F is a linear map for all $A \in \mathbb{V}$.

(c) For which $A \in \mathbb{V}$ is the map $F : \mathbb{V} \rightarrow \mathbb{R}$ given by $F(B) = (B|A)$ an isometry? (Here, $\mathbb{R}$ is equipped with the standard scalar product.)

Answer: Since an isometry is injective, there is no isometry from $\mathbb{V}$, which is of dimension 4, to $\mathbb{R}$, of dimension one (e.g., by dimension theorem). So for no $A \in \mathbb{V}$ the map F is an isometry.

7. Consider the map $Q : \mathbb{R}^3 \rightarrow \mathbb{R}$ given by

$$Q(\mathbf{x}) = 2x_1^2 + 2x_2^2 + 2x_3^2 + 2x_1x_2 + 2x_1x_3 + 2x_2x_3,$$

where $\mathbf{x} = (x_1, x_2, x_3)$.

(a) Which type of surface in $\mathbb{R}^3$ does $Q(\mathbf{x}) = 22$ give?

(b) Let d be the distance from a point on the surface to the origin. What is the largest value d can take? What is the smallest value d can take?

(a) Write $Q(\mathbf{x}) = (x_1 \ x_2 \ x_3) \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \mathbf{x}^t A \mathbf{x}$

Note $A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$ is symmetric

$$\chi_A(\lambda) = \begin{vmatrix} 2-\lambda & 1 & 1 \\ 1 & 2-\lambda & 1 \\ 1 & 1 & 2-\lambda \end{vmatrix} = \begin{vmatrix} 4-\lambda & 4-\lambda & 4-\lambda \\ 1 & 2-\lambda & 1 \\ 1 & 1 & 2-\lambda \end{vmatrix} = (4-\lambda) \begin{vmatrix} 1 & 1 & 1 \\ 1 & 2-\lambda & 1 \\ 1 & 1 & 2-\lambda \end{vmatrix}$$

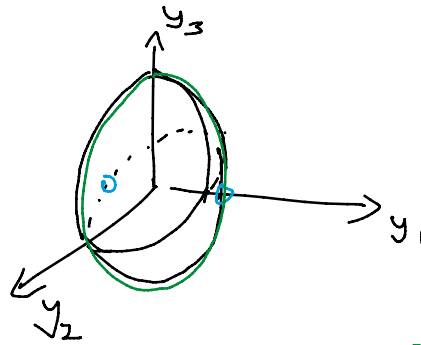
$$= (4-\lambda) \begin{vmatrix} 1 & 1 & 1 \\ 0 & 1-\lambda & 0 \\ 0 & 0 & 1-\lambda \end{vmatrix} = (4-\lambda)(1-\lambda)^2$$

spectral thm

$\Rightarrow \exists$ ON basis $\mathbf{v}$ s.t.
 $[A]_{\mathbf{v}}^{\mathbf{v}} = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$

Thus, for some (ON) coordinates y_1, y_2, y_3 , the surface is given by $4y_1^2 + y_2^2 + y_3^2 = 22$ and thus is an ellipsoid.

... $\Rightarrow 4y_1^2 + y_2^2 + y_3^2 = 22$ and thus is an ellipsoid.



(b)

Smallest $d = \sqrt{\frac{22}{4}}$

Largest $d = \sqrt{22}$

8. Consider the following system of differential equations.

$$\begin{cases} y_1' = y_1 + 4y_2, \\ y_2' = 2y_1 + 3y_2, \end{cases}$$

(a) Find all solutions to the system.

(b) Find the solution that satisfies $y_1(0) = -1, y_2(0) = 2$.

(a) write $y' = \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix} y$

$A = \begin{pmatrix} 1 & 4 \\ 2 & 3 \end{pmatrix}$ has $\chi_A(\lambda) = \begin{vmatrix} 1-\lambda & 4 \\ 2 & 3-\lambda \end{vmatrix}$

$$= (1-\lambda)(3-\lambda) - 4 \cdot 2$$

$$= \lambda^2 - 4\lambda + 3 - 8$$

$$= (\lambda - 5)(\lambda + 1)$$

So A is diagonalizable and we can solve the system!

Let's find an eigenbasis $v = (v_1, v_2)$

$v \in V$ is eigenvector for $\lambda_1 = 5 \Leftrightarrow \begin{pmatrix} -4 & 4 \\ 2 & -2 \end{pmatrix} v = 0$

Take $v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

..

$\lambda_2 = -1 \Leftrightarrow \begin{pmatrix} 2 & 4 \\ 2 & 4 \end{pmatrix} v = 0$

Take $v_2 = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$

$T^{-1} = \frac{1}{5} \begin{pmatrix} 1 & 4 \\ 2 & -1 \end{pmatrix}$

(11)

Then $D = T^{-1} A T = \begin{pmatrix} 5 & 0 \\ 0 & -1 \end{pmatrix}.$

where $T = T_{\underline{e}}^{\underline{v}} = \begin{pmatrix} 1 & 2 \\ 1 & -1 \end{pmatrix}.$

So for $z = T^{-1}y$, we have

$$T z' = y' = A T z \Leftrightarrow z' = T^{-1} A T z = D z$$

$$(\Rightarrow) \begin{cases} z_1' = 5 z_1 \\ z_2' = -z_2 \end{cases}$$

The latter is solved as $\begin{cases} z_1 = c_1 e^{5t} \\ z_2 = c_2 e^{-t} \end{cases}$ for $c_1, c_2 \in \mathbb{R}.$

$$\text{The solutions are } \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = T z = \begin{pmatrix} 1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \begin{pmatrix} c_1 e^{5t} + 2 c_2 e^{-t} \\ c_1 e^{5t} - c_2 e^{-t} \end{pmatrix}$$

for $c_1, c_2 \in \mathbb{R}$

(b) Condition says

$$y_1(0) = c_1 + 2c_2 = -1$$

$$y_2(0) = c_1 - c_2 = 2, \quad \text{so } c_1 = 1, c_2 = -1.$$

Thus the solution is $y_1(t) = e^{5t} - 2e^{-t}$
 $y_2(t) = e^{5t} + e^{-t}$